

# Radar Distance / Level Sensor EM410-RDL

User Guide





#### **Safety Precautions**

Milesight will not shoulder responsibility for any loss or damage resulting from not following the instructions of this operating guide.

- The device must not be disassembled or remodeled in any way.
- In order to protect the security of the device, please change the device password when first configuration. Default password is 123456.
- The device is not intended to be used as a reference sensor, and Milesight won't should responsibility for any damage which may result from inaccurate readings.
- Do not place the device near naked flames, heat source (such as oven), or expose it to sunlight, cold source, liquid, and with extreme temperature changes.
- Do not place the device in places where the temperature is below/above the operating range.
- Remove the battery from the device if it is not to be used for an extended period. Otherwise, the battery might leak and damage the device.
- The device must never be subjected to shocks or impacts.

### **Declaration of Conformity**

EM410-RDL is in conformity with the essential requirements and other relevant provisions of the CE, FCC, and RoHS.









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# **Revision History**

Date	Doc Version	Description
Sept. 12, 2024	V1.0	Initial version



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## 1. Product Introduction

#### 1.1 Overview

EM410-RDL is a non-contact Radar Distance/Level Sensor that adopts Millimeter Wave Radar technology. By measuring millimeter-wave signals at higher frequencies, it provides more stable performance over longer distances, and is less affected by environmental conditions. It can detect the distance between the sensor and liquid of various types, unaffected by temperature, dust, condensate etc. With IP68 waterproof and sealed enclosure, it can withstand the worst environment, while maintaining the measurement accuracy, and does not require routine maintenance.

Milesight offers LoRaWAN® version and Cellular version to meet different communication needs. The LoRaWAN® version can be integrated with Milesight LoRaWAN® gateway and Milesight Development Platform, enabling remote and visual management of all sensor data. The Cellular version supports multiple application modes to be compatible with IoT platforms.

EM410-RDL can used in sewers, rivers, impounding reservoir, storage tanks and other locations that require to measure distance and level.

## 1.2 Features

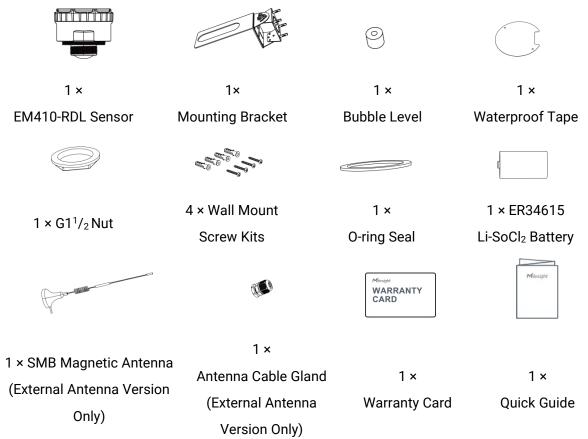
- 8° Radar beam angle can be focused on the target fluid, enabling accurate measurement of liquid level
- Wide measuring range of 0.3m to 12m with small blind zone
- Not affected by dust, condensate, temperature, acoustic noise, etc
- Non- invasive liquid level monitoring, can detect hazardous or non-hazardous liquids
- External antenna or internal antenna versions are optional for various applications
- Built-in 3-axis accelerometer sensor to monitor device tilt status
- Support to check radar-echo curve and one-click diagnostic to calibrate the distance, ensuring the accurate measurement under different environments
- Support blind zone alarm when the ranging results are within the blind zone
- Adopt PVDF material, offering excellent corrosion resistance, wear resistance and compressive strength for harsh environments
- IP68 waterproof design, resistant in fresh water to a maximum depth of 1m for up to 48 hours
- Thread design for common tank installation without extra accessories needed
- Store up to 4,000 historical records locally and support retransmission to prevent data loss
- Easy configuration via NFC and Bluetooth



- Support management and OTA upgrade via Milesight Development Platform
- Function well with standard LoRaWAN® gateways and network servers (LoRaWAN® Version Only)
- Support cumulative number report function for power saving (Cellular Version Only)
- Support multiple network protocols to be compatible with IoT platforms (Cellular Version Only)

## 2. Hardware Introduction

# 2.1 Packing List

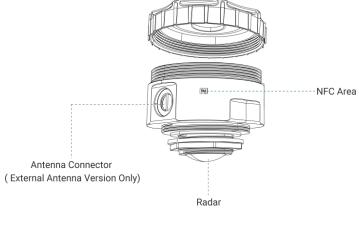


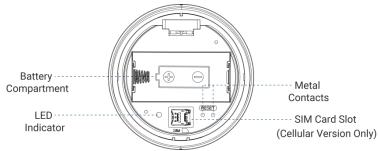
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If any of the above items is missing or damaged, please contact your sales representative.



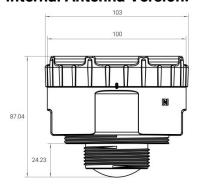
# 2.2 Hardware Overview

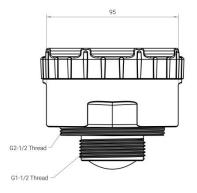


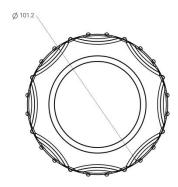


# 2.3 Dimensions (mm)

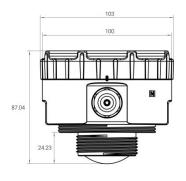
## **Internal Antenna Version:**

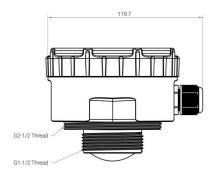


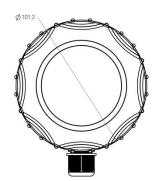




## **External Antenna Version:**









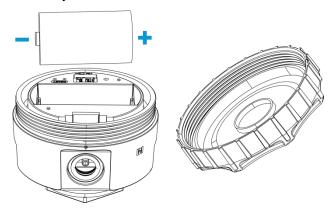
# 2.4 LED Indicator Descriptions

Function	Action	LED Indication
Power On	Install the New Battery	Lights up for 3s
Power Off	Remove Battery	Turns off
Reboot	Create short circuit with the two metal contacts for over 3s	Blinks Slowly
Reset to Factory Default  Create short circuit with the two metal contacts for over 10s		Blinks Quickly
Check On/Off Status	Create short circuit with the two metal	Light On: Device is on
	contacts within 3s	Light Off: Device is off

## 3. Accessories Installation

# 3.1 Battery Installation

Unscrew the top cover counterclockwise, install the batteries according the following picture, the device will turn on automatically and the LED indicator will turn on for 3s.



#### Note:

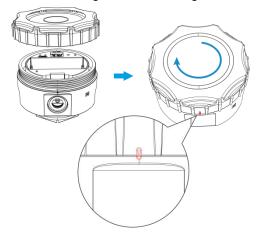
- The device can only be powered by ER34615 Li-SoCl<sub>2</sub> battery. The alkaline battery is not supported.
- The battery should be removed from the device if it is not used for an expended period.

# 3.2 Waterproof Cover Fixed

Attach the waterproof cover to the device with aligning the two red dots as shown in the diagram, and press waterproof cover firmly with your hand.

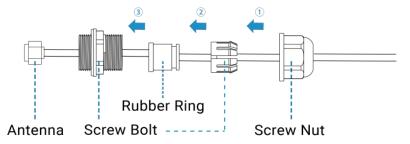


Screw the top cover clockwise until the edge marks are aligned.

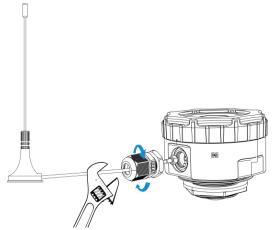


# 3.3 Antenna Installation (External Antenna Version Only)

Install the waterproof connector as shown in the diagram:



And then connect the antenna to antenna connector of the device and use an adjustable wrench to tighten the waterproof connector.





# 4. Operation Guide

# 4.1 NFC & Bluetooth Configuration

After the device is powered on, it can be configured via Bluetooth or NFC. Bluetooth is recommended for the first time installation.

## **Bluetooth Configuration:**

- 1. Download and install "Milesight ToolBox" App on an Bluetooth-supported smart phone.
- 2. Enable Bluetooth and location function on the smart phone.
- 3. Open "Milesight ToolBox" App, select Bluetooth method and search for the target device to connect, and then enter the Bluetooth password to read/write the device until App shows a successful prompt. It's suggested to configure a device password for security. (Default password: 123456)



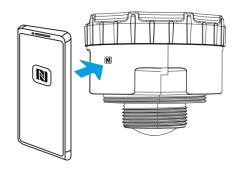
#### Note:

- 1) The Bluetooth connection will be terminated if there's no data interaction within 3 minutes. It will request to connect again.
- 2) The device can connect to only one phone via Bluetooth. For example, if the device is connected to smart phone A via Bluetooth, the connection will be terminated after it is connected to smartphone B.

#### **NFC Configuration:**

- 1. Download and install "Milesight ToolBox" App on an NFC-supported smart phone.
- 2. Enable NFC on the smartphone and open "Milesight ToolBox" App.
- 3. Open "Milesight ToolBox" App, attach the smartphone with NFC area to read/write the device until App shows a successful prompt. It's suggested to configure a device password for security. (Default password: 123456)





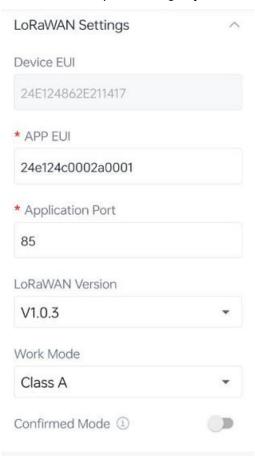
4. Basic information and settings of devices will be shown on ToolBox if it's recognized successfully.

#### Note:

- 1) Ensure the location of smartphone NFC area and it's recommended to take off phone case.
- 2) If the smartphone fails to read/write configurations via NFC, keep the phone away and back to try again.

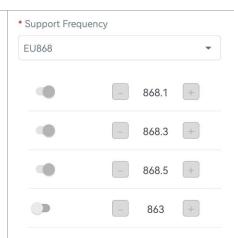
# 4.2 LoRaWAN® Settings

Go to **Device > Setting > LoRaWAN Settings** of ToolBox App to configure join type, App EUI, App Key and other information. You can also keep all settings by default.





Parameters	Description	
Device EUI	Unique ID of the device which can also be found on the label.	
App EUI	Default App EUI is 24E124C0002A0001.	
Application Port	The port used for sending and receiving data, default port is 85.	
LoRaWAN Version	V1.0.2, V1.0.3 are available.	
Work Mode	It's fixed as Class A.	
Confirmed Mode	If the device does not receive ACK packet from network server, it will resend data once.	
Join Type	OTAA and ABP mode are available.	
Application Key	Appkey for OTAA mode, default is 5572404C696E6B4C6F52613230313823.	
Rejoin Mode	Reporting interval ≤ 35 mins: the device will send a specific number of LinkCheckReq MAC packets to the network server every reporting interval or 2*reporting interval to validate connectivity; If there is no response, the device will re-join the network.  Reporting interval > 35 mins: the device will send a specific number of LinkCheckReq MAC packets to the network server every reporting interval to validate connectivity; If there is no response, the device will re-join the network.  Note: Only OTAA mode supports rejoin mode.	
Set the number of	When rejoin mode is enabled, set the number of LinkCheckReq packets sent.	
packets sent	Note: the actual sending number is Set the number of packets sent + 1.	
Network Session Key	Nwkskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.	
Application Session Key	Appskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.	
Device Address	DevAddr for ABP mode, default is the 5 <sup>th</sup> to 12 <sup>th</sup> digits of SN.	
Channel	Enable or disable the frequency to send uplinks.	



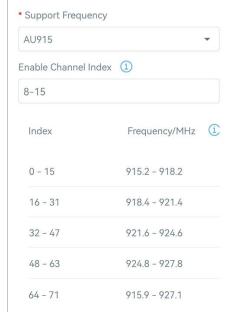
If frequency is one of CN470/AU915/US915, enter the index of the channel that you want to enable and make them separated by commas.

#### **Examples:**

- 1, 40: Enabling Channel 1 and Channel 40
- 1-40: Enabling Channel 1 to Channel 40
- 1-40, 60: Enabling Channel 1 to Channel 40 and Channel 60

All: Enabling all channels

Null: Indicates that all channels are disabled



ADR Mode	Allow network server to adjust datarate of the device.
Spread Factor	If ADR is disabled, the device will send data via this spread factor.
Tx Power	Transmit power of device.
RX2 Data Rate	RX2 data rate to receive downlinks.
RX2 Frequency	RX2 frequency to receive downlinks. Unit: Hz

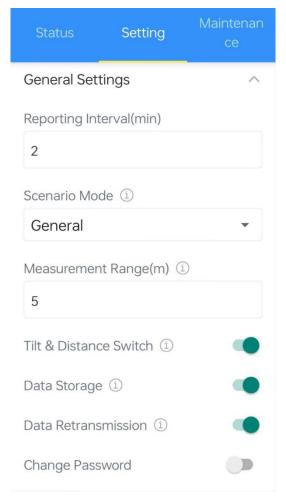
#### Note:

- 1) Please contact sales for device EUI list if there are many units.
- 2) Please contact sales if you need random App keys before purchase.



# 4.3 General Settings

Go to **Device > Setting > General Settings** of ToolBox App to change the reporting interval, etc.



Parameters	Description
Reporting Interval	Reporting interval of transmitting data to server.
	Default: 1440 minutes, range: 1~1440 minutes.
	Select from Standard Mode, Rainwater Well or Wastewater Well.
Scenario Mode	General: Suitable for calm liquid surfaces
	Rainwater Well: Suitable for rainwater well
	Wastewater Well: Suitable for wastewater well
Measurement Range(m)	The maximum distance between target surfaces and device.
Tilt & Distance	When detecting that the offset angle is greater than 15 degrees, turn off
Switch	the distance measuring function.
<u>Data Storage</u>	Disable or enable data storage locally.

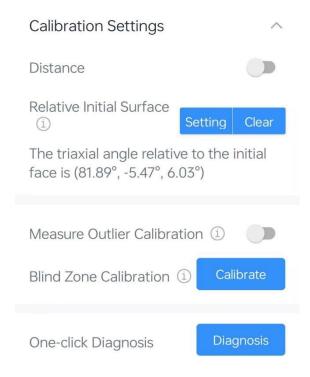


<u>Data</u> <u>Retransmission</u>	Enable or disable data retransmission.
Change Password	Change the password for ToolBox App to access this device.

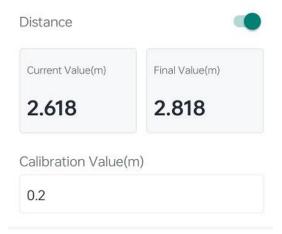
# 4.4 Advanced Settings

## 4.4.1 Calibration Settings

Go to **Device > Setting > Calibration Settings** to enable calibration.



• Numerical Calibration: users can define calibration value to correct every distance.

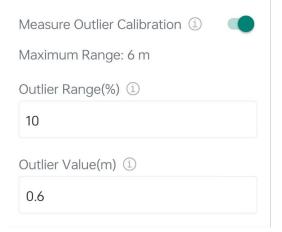


 Relative Initial Surface: Click Setting to read the triaxial angle relative to the current surface, to adjust the current device position as "Normal".





Measure Outlier Calibration: users can define either outlier range or outlier value. When the
device distance value exceeds the outlier range (or range) compared to the previous value,
the device will measure the distance once again. Outlier Value=Max.Range\*Outlier Range.



Blind Zone Calibration: If calibrated, an alarm packet will be reported once if the liquid level
distance falls within the blind zone. Please ensure there is not any objects within the blind
zone when calibration and it is recommended to calibrate it after device installation.



• One-click Diagnosis: This only appears when connecting device via Bluetooth mode. When the collected distance is not consistent with the actual situation, you can use this function.



Step 1: Click to show the current Radar Echo Curve. If the collected distance has only one value, it means the nearest signal amplitude is equal to the strongest signal. If two values appear, it means one represents the nearest signal amplitude and another represents the strongest signal.



Step 2: Choose a collected distance value that is closer to the actual distance, and click to finish configuration or click Refresh to get a new collected distance.

Step 3: If the distance value is still not accurate, click Manual Diagnosis to set the relevant parameters:

Final Distance	2.937m
Radar Echo Signal Quality ①	
10	
Algorithm Threshold Sensitivity	(i)
0.8	
Peak Sorting ①	
Strongest Peak	•



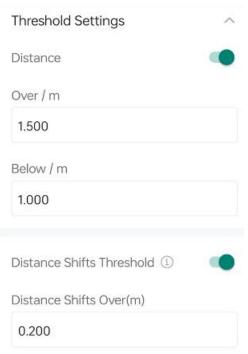
Parameters	Description
	If the liquid level has significant foam, numerous foreign objects, or the
Radar Echo Signal	measurement signal is unstable and the peak is not clear, adjust this
Quality	value upwards.
	Note: The larger the value, the greater the power consumption.
	The device requires only one target to measure. When a large number
Algorithm Threshold	of targets are detected, the sensitivity can be appropriately decreased;
Sensitivity	when no targets are detected, the sensitivity can be appropriately
	increased.
	According to the radar echo curve and the actual scene situation, the
Peak Sorting	peak with the nearest signal amplitude or the strongest peak can be
	selected as the effective target.

Note: If appear "Disabled", reset Relative Initial Surface or disable Tilt & Distance Switch.

Step 4: When adjusting parameters, click to confirm the final distance value. Once you've obtain the desired final distance value, click the arrow on the upper left corner to return to the home page.

# 4.4.2 Threshold Settings

Go to **Device > Setting > Threshold Settings** to configure distance threshold or distance shifts threshold settings.





Collecting Interval(min)	
1	
Alarm Reporting Times	
1	
Alarm Dismiss Report ①	

Parameters	Description
Distance	When the distance is over or below the threshold value, the device will report alarm packets.
Distance Shifts Threshold	When this function is enabled, the device will report alarm packets when the absolute value of the difference between the two collected values exceeds the set threshold.
Collecting Interval(min)	The interval to detect distance, this should be smaller than or equal to the reporting interval.
Alarm Reporting Times	Set the number of alarm reports to be sent after the threshold is triggered, the default is 1.
Threshold Dismiss Report	When the collected distance value changes from outside the threshold to within the threshold, a threshold release packet will be reported.

## 4.4.3 Data Storage

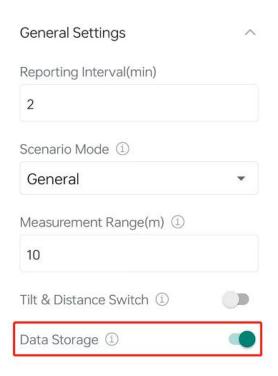
EM410-RDL sensor supports storing more than 2000 data records locally and exporting data via ToolBox App. The device will record the data according to the reporting interval even not joining to network.

Here are the steps for storage:

1. Ensure the device time is correct, click **Sync** to sync the time.



2. Enable **Data Storage** feature.



3. Click **Export Historical Data**, then select the data period and click **Confirm** to export data. The maximum export data period on ToolBox App is 14 days.



#### 4.4.4 Data Retransmission

EM410-RDL sensor supports data retransmission to ensure the network server can get all data even if the network is down for some time. There are two ways to get the lost data:

- Network server sends downlink commands to enquire the historical data for specifying time range, refer to section <u>Historical Data Enquiry</u>.
- When the network is down if no response from LinkCheckReq MAC packets for a period of time, the device will record the network disconnected time and re-transmit the lost data after the device re-connects the network.

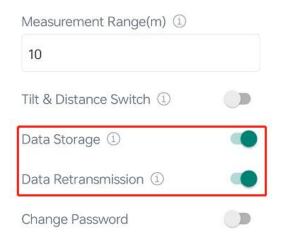


Here are the steps for retransmission:

1. Ensure the device time is correct, please click **Sync** to sync the time.



2. Enable **Data Storage** and **Data Retransmission** feature.



3. Go to **Device > Setting > LoRaWAN Settings** to enable rejoin mode and set the number of packets sent. For example, the device will send LinkCheckReq MAC packets to the network server regularly to check any network disconnection; if there is no response for 32+1 times, the join status will change to de-activated and the device will record a data lost time point (the time it reconnected to the network).



4. After the network connection is restored, the device will send the lost data from the point in



time when the data was lost according to the data retransmission interval (600s by default).

#### Note:

- 1) If the device is rebooted or re-powered when data retransmission is not completed, the interrupted retransmission data will be retransmitted first after the network is reconnected to the network, and then the newly triggered retransmission data will be transmitted.
- 2) If the network is disconnected again during data retransmission, it will only send the latest disconnection data.
- 3) The retransmission data format is started with "20ce", please refer to section <u>Historical Data Enquiry</u>.
- 4) Data retransmission will increase the uplinks and shorten the battery life.

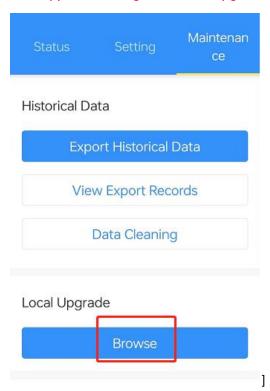
#### 4.5 Maintenance

#### 4.5.1 Upgrade

- 1. Download firmware from Milesight website to your smartphone.
- 2. Open Toolbox App, go to **Device > Maintenance** and click **Browse** to import firmware and upgrade the device.

#### Note:

- 1) The device only supports upgrade via Bluetooth.
- 2) Operation on ToolBox is not supported during a firmware upgrade.

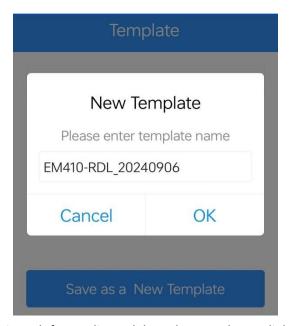




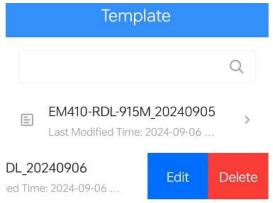
## 4.5.2 Backup

EM410-RDL supports configuration backup for easy and quick device configuration in bulk. Backup is allowed only for devices with the same model and frequency band.

- 1. Go to **Template** page on the App and save current settings as a template. You can also edit the template file.
- 2. Select one template file which saved in the smartphone and click **Write**, then attach to another device to write configuration.



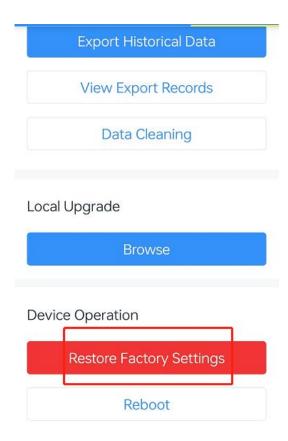
**Note:** Slide the template item left to edit or delete the template. Click the template to edit the configurations.



#### 4.5.3 Reset to Factory Default

Go to **Device > Maintenance** to click **Restore Factory Settings**.



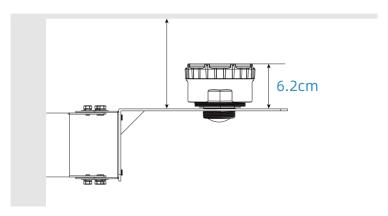


# 5. Installation

# 5.1 Mounting Bracket Installation

#### Step 1: Locate Position

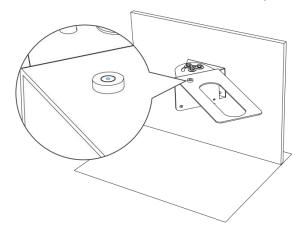
- Avoid placing the device near any metal objects, water outlets, stairs and other obstacles;
- Please consider the height of the equipment and other factors (such as the thickness of the manhole cover) to ensure that the equipment does not interfere with normal usage after installation.



Step 2: Adjust Level

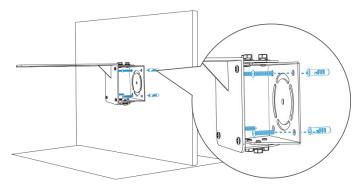


Attach the bubble level to the bracket surface to ensure the bracket is parallel.

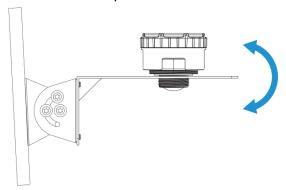


Step 3: Fix Mounting Bracket

Drill 4 holes according to the mounting bracket holes. Fix the wall plugs to the wall holes, then fix the mounting bracket to the wall plugs via mounting screws.

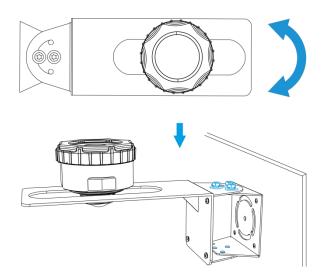


Note: If the wall is tilted, adjust the bracket component direction to 90° as below:



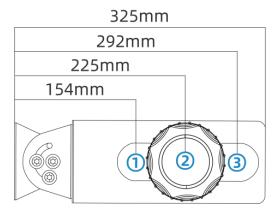
Step 4: Adjust Mounting Bracket Angle

Loosen the two nuts on both the upper and lower tracks of the bracket, adjust the bracket to the appropriate angle, then use a wrench to tighten all six nuts with flat washers.



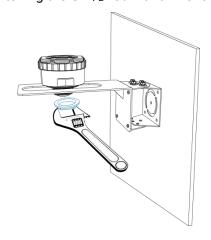
Step 5: Select the device installation location on the bracket according to the installation height.

Installation Height	Recommend Location
1 ~ 2m	1
2.1 ~ 3m	2
3.1 ~ 6m	3



Step 6: Fix Device

Place the device onto the mounting bracket, adjust it to an appropriate position, and then tighten it with  $G1^{1}/_{2}$  nut. The torque for tightening the  $G1^{1}/_{2}$  nut with a wrench should not exceed 4 N •m.

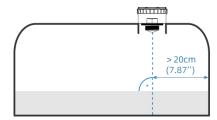




#### 5.2 Tank Installation

#### Step 1: Locate the Device Installation Position

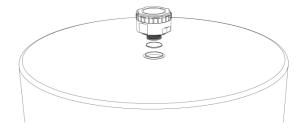
- Place it away from the tank wall more than 20cm;
- Perpendicular to the measured liquid and with no obstacles between the device and the measured liquid.



#### Step 2: Fix Device

The device has G1  $\frac{1}{2}$  and G2  $\frac{1}{2}$  thread opening to allow it to be screwed into an existing applicable thread opening of a tank. An O-ring is supplied and should be used to ensure a watertight seal.

When tanks' mounting hole is unavailable or where it is undesirable to cut a mounting hole in the tank, an adapter can be installed on the top surface of the tank and the sensor can be mounted on this adapter. Adapters for different sized need to be purchased separately. The device should be threaded and screwed onto the adapter firmly to make a good seal. The O-ring shown below seals the non-invasive adapter to the bottom of the sensor's main enclosure.



#### **Installation Note:**

- The installation location of the device should avoid strong vibrations, direct sunlight, and exposure to rain or snow.
- Do not place the device near objects that emit intense heat, strong electromagnetic fields, or radioactive materials.
- 3. It is recommended to attach the magnetic base of external antenna to a manhole cover or other metal surface to ensure a good signal.
- 4. After installation, please check the tilt status and distance measurement in the ToolBox App, and adjust the installation position, direction, or related parameters based on the results:



Advances Settings.

# 6. Communication Protocol

All data are based on following format (HEX), the Data field should follow little-endian:

Channel1	Type1	Data1	Channel2	Type2	Data2	Channel 3	
1 Byte	1 Byte	N Bytes	1 Byte	1 Byte	M Bytes	1 Byte	

For decoder examples please find files on <a href="https://github.com/Milesight-IoT/SensorDecoders">https://github.com/Milesight-IoT/SensorDecoders</a>.

# 6.1 Basic Information

EM410-RDL sensor reports basic information whenever it joins the network.

Channel	Туре	Byte	Description
	0b (Power On)	1	ff
	01 (Protocol Version)	1	01=>V1
	fe (Reset Report)	1	ff
	16 (Device SN)	8	16 digits
ff	09 (Hardware Version)	2	01 00 => V1.0
	0a (Firmware Version)	2	01 14 => V1.14
	Of (Device Type)	1	00: Class A
	ff (TSL Version)	2	0100

#### **Example:**

ff0bff ff0101 fffeff ff166862e21141780013 ff090100 ff0a0101 ff0f00 ffff0100					
Channel	Туре	Value	Channel	Туре	Value
ff	0b (Power On)	ff (Reserved)	ff	01 (Protocol Version)	01 (V1)
Channel	Туре	Value	Channel	Туре	Value
ff	fe (Reset Report)	ff	ff	16 (Device SN)	6791d19 6040500 05
Channel	Туре	Value	Channel	Туре	Value
ff	09 (Hardware Version)	0100 (V1.0)	ff	0a (Firmware Version)	0101 (V1.1)
ff Channel	(Hardware	0100 (V1.0)  Value	ff Channel		



# 6.2 Sensor Data

Channel	Туре	Byte	Description		
01	75(Battery Level)	1	UINT8, Unit: %, [1-100]		
04	82(Distance)	2	INT16, Unit: mm		
05	00(Device Position)	1	00: Normal, 01: Tilt(horizontal offset angle ≥ 15°)		
06	c7(Radar Signal Strength)	2	INT16*0.01, Unit: dBm		
84	82(Distance)	3	<ul><li>Byte 1-2: Distance, INT16, Unit: mm</li><li>Byte 3: 01-Alarm; 00-Alarm dismiss</li></ul>		
94	82(Distance Shifts Threshold)	5	<ul> <li>Byte 1-2: Distance, INT16, Unit: mm</li> <li>Byte 3-4: Distance Shifts, INT16, Unit: mm</li> <li>Byte 5: 02</li> </ul>		
b4	82(Blind Zone)	3	<ul> <li>Byte 1-2: Distance, INT16, Unit: mm</li> <li>Byte 3:         <ul> <li>00-Alarm dismiss</li> <li>01-Alarm</li> <li>No target within 30cm, report distance as fffd</li> <li>Have target within 30cm, report the distance</li> <li>02-Cannot collect the target, report distance as fffd</li> <li>03-Sensor Abnormal, report distance as fffff</li> </ul> </li> </ul>		
20	ce(Historical Data)	11	<ul> <li>Byte 1-4: Unix Timestamp</li> <li>Byte 5-6: Distance, INT16, Unit: mm</li> <li>Byte 7-8: Temperature, INT16*0.1, Unit: °C</li> <li>Byte 9-10: Distance Mutation, INT16, Unit: mm</li> <li>Byte 11: Alarm Status</li> <li>Bit0: Threshold Alarm</li> <li>Bit1: Threshold Alarm Dismiss</li> <li>Bit2: Blind Zone Alarm</li> </ul>		



➤ Bit3: Blind Zone Alarm Dismiss
Bit4: Distance Shifts Threshold Alarm
Bit5: Device Position
➤ Bit6-7: 00

#### **Examples:**

1. Periodic packet:

	017562 0482aa0c 06c70303 050000						
Channel	Туре	Value	Channel	Туре	Value		
01	75 (Battery Level)	62=>98%	04	82 (Distance)	aa0c => 0caa =>3242 mm		
Channel	Туре	Value	Channel	Туре	Value		
06	c7(Radar Signal Strength)	03 03=> 771*0.01=7.71 dBm	05	00(Device Position)	00: Normal		

2. Threshold Alarm: report when distance reaches the threshold.

	8482 c827 01 9482 c827850c 02						
Channel	Туре	Value					
0.4	82	Distance: c8 27 => 27 c8 =10184mm = 10.184m					
84	(Distance)	01= Alarm					
	92(Dietopos	Distance Shifts Threshold: c8 27 => 27 c8					
94	82(Distance Shifts Threshold)	=10184mm = 10.184m					
94		85 0c => 0c 85=3205mm = 3.205m					
		02=Alarm					

3. Blind Zone alarm packet: report when the target value reaches the blind zone.

b482 ac00 01					
Channel	Channel Type Value				
b4	82(Blind Zone)	ac 00 => 00 ac = 172mm = 0.172m			
D <del>4</del>		01=calibrated distance			

## 6.3 Downlink Commands

EM410-RDL supports downlink commands to configure the device. Application port is 85 by default.

Channel	Туре	Byte	Description
ff	10 (Reboot)	1	ff (Reserved)
	bd(UTC Time Zone)	2	INT16/60

28(Quei	ry Device Status)	1	01
	-		Byte 1: 00
8e (Re	8e (Reporting Interval)	3	Byte 2-3: Reporting Interval,
			UINT16, Unit: min, Range: 1~1440
			Byte 1:
			> 00 = General Mode;
			> 01 = Rainwater Well Mode;
1b(Meas	surement Range)	5	> 02 = Wastewater Well Mode
			Byte 2-3: 0000
			Byte 4-5: Max. Measuring Range,
			UINT16, Unit: mm
3e (Tilt &	Distance Switch)	1	01 = Enable; 00 = Disable
68([	Oata Storage)	1	01 = Enable; 00 = Disable
69(Data	Retransmission)	1	01 = Enable; 00 = Disable
6 a/Data Data	6a(Data Retransmission Interval)		Byte 1: 00
oa(Data Reti			Byte 2-3: Interval time, Unit: s
	ab(Distance Calibration)		Byte 1: 01-Enable; 00-Disable
ab(Dista		3	Byte 2-3: Calibration Value, INT16,
			Unit: mm
			Byte 1: Recollecting Times, UINT 8,
1c(Recollecti	ng of Measure Outlier	2	Range: 1~3
С	alibration)	۷	Byte 2: Recollecting Interval, UNIT
			8, Unit: s, Range: 1~10
			Byte 1:
			➤ Bit2~Bit0:
			000-disable
			001-below
			010-over
06 (Set <sup>-</sup>	Threshold Alarm)	9	011-within
			100-below or over
			➤ Bit5~Bit3:
			001-Distance threshold alarm;
			010-Distance shifts threshold
			alarm



			<ul> <li>Bit6: 0</li> <li>Bit7:         <ul> <li>0-disable threshold dismiss</li> <li>report</li> <li>1-enable threshold dismiss</li> <li>report</li> </ul> </li> <li>Byte 2-3: Min. Value, INT16, Unit: mm</li> <li>Byte 4-5: Max. Value or distance shifts value, INT16, Unit: mm</li> </ul>
			Byte 6-9: 00000000
	f2(Alarm Reporting Times)	2	UINT16, Range: 1~1000, Default: 1
	27(Clear History Data)	1	01
	2a(Device Calibration)	1	01-Blind Zone Calibration
	12 (Scenario Mode)	1	00 = General Mode; 01 = Rainwater Well Mode; 02 = Wastewater Well Mode
f9	39(Collecting Interval)	2	Unit: min, Range: 1~1440
19	14(Radar Echo Signal Quality)	2	INT16, Range: -10~35
	15(Algorithm Threshold Sensitivity)	2	INT16*0.1, Range: 0.1~1
	16(Peak Sorting)	1	00-Nearest Peak; 01-Strongest Peak

# Example:

1. Set time zone as UTC-4.

ffbdc0fd				
Channel Type Value				
ff h	bd	c0 fd => fd c0 = -240/60=-4		
"	bu	the time zone is UTC-4		

2. Set reporting interval as 4 minutes.

ff8e 00 0400			
Channel Type		Value	
ff	8e (Reporting Interval)	04 00 => 00 04 = 4 minutes	

3. Reboot the device.



ff10 ff		
Channel	Туре	Value
ff	10 (Reboot)	ff (Reserved)

4. Set the device as Wastewater Well mode.

f912 02		
Channel	Туре	Value
f9 12 (Scenario Mode)		02 = Wastewater Well Mode

5. Disable "Tilt & Distance Switch" feature.

ff3e 00			
Channel	Туре	Value	
ff	3e (Tilt & Distance Switch)	00 = disable	

6. When the distance is below 1m or over 10m, the sensor will send threshold alarm.

ff06 8c e803 1027 00000000				
Channel Type		Value		
	06 (Set Threshold Alarm)	8c=10 001 100:		
		100=below or over		
		001=Distance threshold alarm		
ff		10=enable threshold dismiss report		
11		Min: e8 03 => 03 e8 = 1000 mm		
		= 1m		
		Max: 10 27 => 27 10 = 10000 mm		
		=10m		

7. When the distance shifts is over 0.5m, the sensor will send threshold alarm.

ff06 8c 0000 f401 00000000				
Channel Type		Value		
		8c=10 010 010:		
	06 (Set Threshold Alarm)	010=over		
		010=Distance shifts threshold alarm		
ff		10=enable threshold dismiss report		
		Min: 0000		
		Distance shift value: f4 01 => 01 f4 =		
		500 mm=0.5m		

# 6.4 Historical Data Enquiry

EM410-RDL supports sending downlink commands to enquire historical data for specified time point or within a certain time range. Before utilizing this feature, it is import to make sure the



device time is correct and data storage feature was enable to store the data.

# **Command format:**

Channel	Туре	Byte	Description	
	6b (Enquire data in time point)	4	unix timestamp	
	6c (Enquire data in time range)	8	Byte 1-4: Start time, unix	
fd			timestamp	
lu			Byte 5-8: End time, unix	
			timestamp	
	6d (Stop query data report)	1	ff	
	6a(Report Interval)	З	Byte 1: 01	
ff			Byte 2-3: Unit: s, Range:	
			30~1200s (60s by default)	

# Reply format:

Channel	Туре	Byte	Description	
	6b/6c		00: data enquiry success;	
fc		1	01: time point or time range invalid;	
			02: no data in this time or time range.	
			Byte 1-4: Unix Timestamp	
			Byte 5-6: Distance, INT16, Unit: mm	
			Byte 7-8: Temperature, INT16*0.1,	
			Unit: °C	
	ce (Historical Data)	11	Byte 9-10: Distance Shifts, INT16, Unit:	
			mm	
			Byte 11: Alarm Status	
20			➤ Bit0: Threshold Alarm	
			Bit1: Threshold Alarm Dismiss	
			Bit2: Blind Zone Alarm	
			Bit3: Blind Zone Alarm Dismiss	
			Bit4: Distance Shifts Threshold	
			Alarm	
			Bit5: Device Position	
			➤ Bit6-7: 00	



#### Note:

- 1. The device only uploads no more than 300 data records per range inquiry.
- 2. When enquiring about the data in time point, it will upload the data that is the closest to the search point within the reporting interval range. For example, if the device's reporting interval is 10 minutes and users send a command to search for 17:00's data, if the device finds there is data stored in 17:00, it will upload these data. If not, it will search for data between 16:50 to 17:10 and upload the data which is the closest to 17:00.

#### Example:

1. Enquire historical data between 2024/9/7 15:28:22 to 2024-9-11 15:28:22.

fd6c 9600dc66 9646e166				
Channel Type Value				
£-1	6c (Enquire data in time	Start time: 9600dc66 => 66dc0096 = 1725694102s =2024/9/7 15:28:22		
fd	range)	End time: 9646e166 => 66e14696 =1726039702 s		
		=2024-9-11 15:28:22		

#### Reply:

fc6c00			
Channel Type Value			
fc	6c (Enquire data in time range)	00: data enquiry success	

20ce b443e166 ac0c be00 0000 20				
Channel	nannel Type Time Stamp		Value	
20	ce (Historic al Data)	b443e166 => 66e143b4 = 1726038964s = 2024-9-11 15:16:04	Distance: ac0c => 0cac =3244mm=3.244m Temperature: be00 => 00be = 190*0.1=19°C Distance shifts: 0000 Alarm Status: 20=0010 0000=>Tilt	

-----END-----